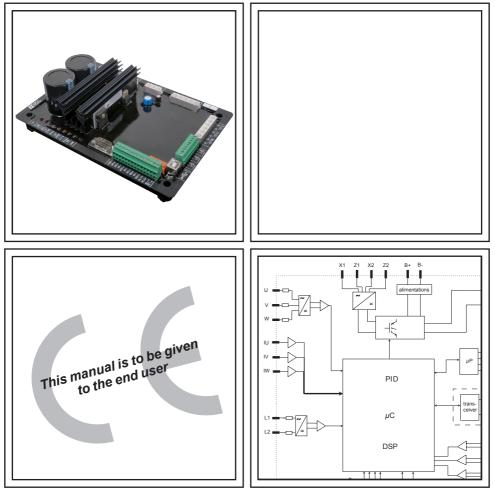


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D510 C

Automatic Voltage Regulators (AVRs)

Installation and maintenance

This manual concerns the alternator AVR which you have just purchased.

We wish to draw your attention to the contents of this maintenance manual. By following certain important points during installation, use and servicing of your alternator, you can look forward to many years of trouble-free operation.

SAFETY MEASURES

Before using your machine for the first time, it is important to read the whole of this installation and maintenance manual.

All necessary operations and interventions on this machine must be performed by a qualified technician.

Our technical support service will be pleased to provide any additional information you may require.

The various interventions described in this manual are accompanied by recommendations or symbols to alert the user to potential risks of accidents. It is vital that you understand and take notice of the various warning symbols used.

This AVR can be incorporated in a CE-marked machine.



Warning symbol for an operation capable of damaging or destroying the machine or surrounding equipment.



Warning symbol for general danger to personnel.



Warning symbol for electrical danger to personnel.

Note: LEROY-SOMER reserves the right to modify the characteristics of its products at any time in order to incorporate the latest technological developments. The information contained in this document may therefore be changed without notice.



Installation and maintenance

D510 C Automatic Voltage Regulators (AVRs)

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All servicing or repair operations performed on the AVR should be undertaken by personnel trained in the commissioning, servicing and maintenance of electrical and mechanical components.

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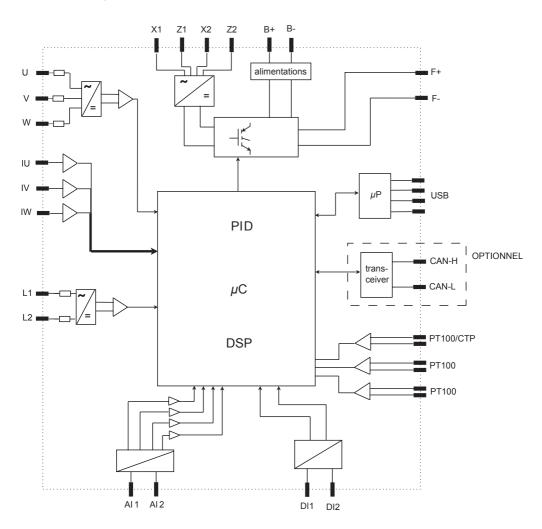
Installation and maintenance

D510 C Automatic Voltage Regulators (AVRs)

1 - PRESENTATION

1.1-Operation

A schematic diagram of the D510 appears below.





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Terminals	Signals	Scheme
X1 X2 Z1 Z2	Power supply - Auxiliary winding input - PMG input - SHUNT input	Up to 180V $Z1$ A $D510$ $D510$
L1 L2	Mains voltage measurement	Up to 530V
U V W	Alternator voltage measurement For single-phase: use V and W	Alt BMΩ ± 16V
IU = (s1, s2) IV = (s1, s2) IW = (s1, s2)	Alternator current measurement	
Al1 Al2	Analog inputs: External setting	Al1 or Al2 10 ±26V +20MA 866Ω 0-10V 210kΩ ± 10V 10kΩ
DI1 DI2	Digital inputs: U=U and PF/kVAR regulation	0V +15V 2 <i>k</i> 21 DI1/DI2
B+ B-	DC power supply	B+ • • • • • • • • • • • • • • • • • • •



D510 C Automatic Voltage Regulators (AVRs)

Terminals	Signals	Scheme
F+ F-	Field excitation: 6 A up to 15 A/10 s	F+•
CTP PT100_1 PT100_2 PT100-3	Temperature sensor	PT100 CTP 4k75 ± ØV
CAN_H CAN_L	CAN BUS	Η μΡ CAN Transceiver
USB_D+ USB_D-	USB 2.0 communication port	$\begin{array}{c c} +5V \\ \hline D_{-} \\ \hline D_{+} \\ 0V \\ \hline \end{array} \\ \hline USB \\ Controller \\ \hline \end{array}$



• **Power:** It varies according to the type of field excitation (3 types).

-*AREP*: The AVR is powered by two auxiliary windings which are independent of the voltage sensing circuit.

The first winding has a voltage in proportion with that of the alternator and the second has a voltage in proportion with the stator current.

- *PMG*: A permanent magnet generator (PMG) added to the alternator supplies the AVR with voltage which is independent of the main alternator winding.

- SHUNT: The AVR is powered by the main winding (140 V - 50/60 Hz).

10A fast fuses externally mounted the D 510C must be used in the three cases.

• Battery: This is used to supply the AVR with between 11 V and 30 V. It must always be present.

The battery supply must be protected by a 1 A temporised fuse-

• **Mains:** This input is dedicated to the measure phase-to-phase mains voltage which will be taken as the reference when voltage matching is performed.

• Alternator voltage: This input measures the alternator output voltage to the AVR in: - three-phase (U, V, W) - single-phase (V, W)

• **Current transformer(s):** This input measures the current supplied by the alternator. **It must always be present** when the alternator is running in parallel operation or at PF or KVAR regulation or stator current

limitation.

- The possible configurations are:
- 1 CT on phase U
- 3 CTs on phases U, V and W

• **Temperature sensor(s):** These are used to measure the alternator temperature and alert the user if there is a rise in temperature. This measurement can be taken either with 1 PTC or 3 PT100s.

Communication:

- *USB port*: This is used to connect the AVR to a computer and creates the link between the EasyReg software and the D510.

- *CAN port*: This is used to connect the AVR to a bus CAN interpreter in order to exchange parameters with the D510.

The CAN link is only available in the CAN version identified by the letter C (eg: D510-C).

I/O: This part is used to:

- Enter settings
- Send information from the D510
- Receive information from the alternator

• **LEDs:** These light-emitting diodes inform the user whether the AVR is working correctly or not.



D510 C Automatic Voltage Regulators (AVRs)

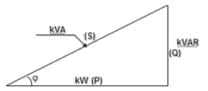
1.2 - Characteristics

The different functions of the D510 are:

- Voltage regulation
- Regulation of the power factor (PF)
- Regulation of the reactive power
- Manual regulation (lexc)

• **Voltage regulation:** The D510 regulates the alternator output voltage. Regulation is applied to the mean value or the true rms value (TRMS).

• Regulation of the power factor: The D510 regulates the power factor. This is the ratio between the active power ($P = \sqrt{3^*U^*I^*\cos \phi}$) and the apparent power ($S = \sqrt{3^*U^*I}$).



- Inductive P.F. [0; $\pi/2$] means that the current is lagging behind the voltage. The load is inductive (induction motor, transformer, etc).

- Capacitive P.F. $[\pi/2; \pi]$ means that the current is leading the voltage. The load is capacitive (fluorescent lighting, etc).

• Regulation of the reactive power: The D510 regulates the reactive power $(Q = \sqrt{3*U*I*sin \phi})$ at a fixed value.

• **Manual regulation:** The D510 can regulate the excitation current.

These functions are selected when setting the AVR parameters.

1.3 - Specifications

I.3.1 - Characteristics			
Name	Minimum value	Maximum value	Adjustable
Battery power supply	11 V	30 V	-
Alternator frequency	10 Hz	100 Hz	Yes
Mains frequency	10 Hz	100 Hz	-
Single-phase mains voltage	50 V	530 V	-
Mains voltage ratio	1	100	Yes
Excitation current	0 A	6 A	-
Max. excitation current	0 A	15 A/10s	-
Single-phase alternator voltage	0 V	530 V	-
Three-phase alternator voltage	0 V	530 V	-
Alternator current input	1 A	5 A	Yes
Alternator I u	0 A	5000 A	-
Alternator I v	0 A	5000 A	-
Alternator I w	0 A	5000 A	-



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Name	Minimum value	Maximum value	Adjustable
LAM knee-point	37 Hz*	100 Hz*	Yes*
Adjustable LAM	70% of Voltage reference	100% of Voltage reference	Yes
Variable U/F	1.0	3.0	Yes
Voltage reference setpoint	90 V	530 V**	Yes
Adjustment of external accuracy	- 10%***	+ 10%***	Yes**
Quadrature droop	0%	+ 10%	Yes
Soft start acceleration	0.1 s	120 s	Yes
Loading acceleration	0.1 s/10 Hz	30.0 s/10 Hz	Yes
Voltage drop compensation	0%	10%	Yes
Excitation current manual reference	0 A	10 A	Yes
Rated cosine P.F.	-0.6 (LEAD)	+0.6 (LAG)	Limited by settings
kVAR	-100%	+100%	Limited by settings
Proportional action	0*	1500*	Yes*
Integral action	0*	200*	Yes*
Derivative action	0*	12000*	Yes*
Profit	0*	100*	Yes*
Scale	1/50*	1/1*	Yes*

* in expert mode - ** without voltage transformer - *** 30% in expert mode

1.3.2 - Status and faults

Name	Minimum value	Maximum value	Adjustable
Short-circuit delay	0.5s	10s	no
Short-circuit excitation current demand	0A	10A	no
Underexcitation delay	0.1s	5.0s	no
I EXC SHUT down	0A	5A	no
Overvoltage time	0s	100s	no
Overvoltage threshold	0%	120%	no
PT100 temperature	0°Celsius	250°Celsius	-
PT100 temperature threshold	50°C	200°C	-
PTC input	0%	100%	-

1.3.3 - Environments

Storage temperature : -55°C +85°C Functioning temperature : -40°C +65°C



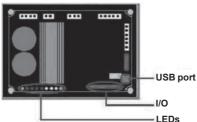
Installation and maintenance

D510 C Automatic Voltage Regulators (AVRs)

2 - HUMAN-MACHINE INTERFACE

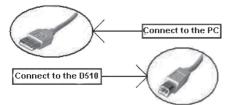
The D510 human-machine interface consists of 3 elements:

- The USB link
- The I/O
- The LEDs



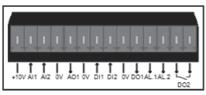
2.1 - Communication USB link

The EasyReg software and the D510 communicate via a USB cable (Universal Serial Bus).



2.2 - Analog I/O

This part of the board allows the operator to use the inputs to make manual settings and the outputs to check certain data or to indicate whether certain AVR functions are working correctly or not. An external voltage (0 V - 10 V) is present which can be used as a reference for an electronic device.



The minimum analogic input setting is 0% and the maximum is 100%.

External by setting is either:

- from an external potentiometer (1k Ω),

- 4 20 mA,
- 0 10 V,
- ± 10V.

The two analog inputs can also be used to achieve digital functions + / -.

NB : make sure that the voltage applied on analogue input does not exceed 10V.

2.3 - Digital I/O

E/S	Туре	Characteristics
DI ₁ DI ₂	Pull up input	To be connected to 0V
DO ₁	Opened collector	Max current: 60mA Voltage: 0 - 24V
DO ₂	Dry contact	6A, 30Vdc/250V AC (on resistor)
AL ₁ AL ₂	Opened collector	Max current: 60mA Voltage: 0 - 24V

2.4 - LEDs

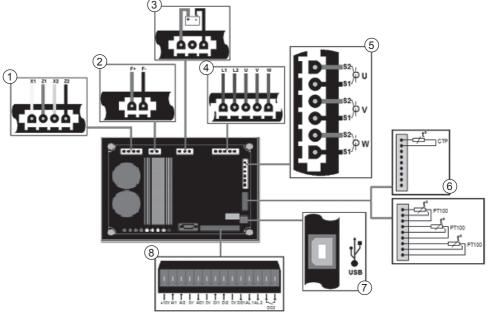
The LEDs serve to inform the user whether the AVR is working correctly or not.

Name	Colour	Meaning
Power ON	Green	The board is supplied with power
↓ Hz	Red	Speed drop
$\uparrow / \downarrow \text{Volt}$	Red	Problem of overvoltage or undervoltage
↑ / ↓ Exc.	Red	Problem of overexcitation or underexcitation
	Red	Problem on the exciter field diode bridge
Manu	Yellow	Manual mode enabled
PF / KVAR	Yellow	Regulation of the power factor or reactive power enabled
U = U	Yellow	Alternator voltage = Mains voltage
USB	Blue	AVR connected to a PC



2.5 - Wiring scheme

AVR connections:



- 1-Power:
 - AREP : Yellow wire on X2 red wire on Z1 green wire on X1 black wire on Z2
 - PMG : X2, X1 and Z2
 - SHUNT : X1 and X2
- 2- Field excitation: The field winding + to the terminal F+ The field winding - to the terminal F-
- 3- Battery: Ensure the polarity is correct when connecting
- 4- Voltage sensing:
 - Mains voltage: L1 and L2
 - Alternator voltage: single-phase: V and W

- three-phase: U, V and W

- 5- Current transformer(s):
 - Placing in parallel and measurement: CT on U
 - Measurements: CTs on V and W
- 6- Temperature sensor:
 - PTC: see mounting above
 - PT100: see mounting above
- 7- USB port
- 8- Digital I/O



Installation and maintenance

D510 C Automatic Voltage Regulators (AVRs)

3 - SETTING THE FUNCTION PARAMETERS

EasyReg is a Leroy Somer Software which allows to :

 Easily configure the digital regulator D510
 Monitor several important parameters such as alternator output voltage, excitation current, active and reactive power, etc...

- Optimize the regulation loop

- Set the AVR parameters.

- Configure the inputs and outputs.

- Display faults and parameter measurements.

It is the interface between the user and the digital AVR.

3.1 - Installation

Double click on the installer EasyReg and follow the installation instructions.

3.2-Startup

Connect the AVR to the computer with a USB cable. Check that the blue «USB» LED is on.

To start the software, go to «Start», «Programs» then «EasyReg».



3.3-Appearance

The regulator is connected to the PC via standard USB cable, the blue LED (labeled LED) of the regulator is then ON and the information « D510C CONNECTED » is displayed on the screen left bottom.





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There are four options when using this software:

- New configuration
- Open a configuration from a file
- Open a configuration from the pre-programmed AVR.
- Create customised configuration (Expert mode)

∆ ĭ	EasyReg		
Fil	e Edit Parameters ?		
b	New configuration	Ctrl+N	
\star	New customised configuration		
Ê	Open	•	🗃 as from a file 🛛 Ctrl+O
	Save	Ctrl+S	as from a D500
R	Save as	Ctrl+Shift+S	
	Properties		
۲	Print	Ctrl+P	

If the AVR is not connected or has never been configured, it is impossible to «Open from a D510».

PROPERTIES

The user can choose to lock the regulator to avoid the configuration modification. In that case, the configuration name and a lock code must be entered.

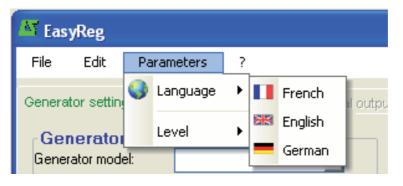
PRINT

The configuration can be edited in a Word or PDF format file.

3.3.1 - Languages and modes

3.3.1.1 - Languages

Three languages are available on EasyReg: French , English and German.





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D510 C Automatic Voltage Regulators (AVRs)

3.3.1.2 - Modes

Two operation modes are possible:

- Standard mode by default
- Expert mode which offers additional functions

This mode is reserved for users who possess the skills to make certain more complex adjustments or to use the AVR in a wider range of operating conditions.

👫 Eas	yReg	
File	Edit	Parameters ?
		🜒 Language 🔸
		Level 🗸 🕨 🗸 Standard
		Expert

If you require the Expert mode access code, please use the main menu: click on « ? » then « About... ». The following window is displayed

🖉 About		$\mathbf{\overline{X}}$
	Software: EasyReg.exe	
	Revision: 2.20	
	Developed by: Leroy Somer	
1998 A	D500 Software Version:	
	PC code: 100424PBPB01ECCP517L	Copy code
	www.leroy-somer.com	OK (22 s)

Click on« Copy code » and email the PC code to: <u>SupportTechniqueSillac.IALS@Emerson.com</u> The access code will be sent you back.

Incorrect settings can harm the AVR and the alternator and can cause serious damage (to users, loads). Select the duty type and the class according to your specification.

3.3.2 - Saving and loading the configuration

Save your configuration (for the 1st time):

- Go into the «File» menu and click «Save As»

- Choose where you wish to save to
- Name your saved configuration
- Click Save As

Subsequently, to save the configuration, you just need to go into the «File» menu and click «Save».



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D510 C Automatic Voltage Regulators (AVRs)

Send the configuration to the AVR:

- check that the AVR is connected correctly (blue LED on) at the bottom left-hand side of the screen.

- go into the «Edit» menu.
- Go to : PC --> D510 • D510 --> PC
- click « PC -> D510 ». Wait for loading to complete.

🔤 Eas	yReg		
File	Edit Parame	eters ?	
Genera	D500->PC		Faults and digital outputs Monitors
Gener	P(>D500 Terator ator model:	F10	

3.3.3 - New configuration

There are two possible configuration levels: standard or expert.

By default, the software is in standard mode. The AVR is programmed step by step. Access

3.3.3.1 - Alternator Configuration

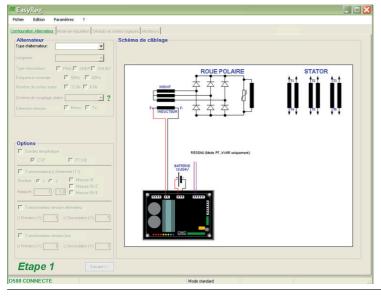
to the «Regulation Mode» page is only possible if the «Alternator Configuration» page has been filled in. The program is transferred to the D510 via the «Edit» menu then «PC => D510» or by pressing F10 on the keypad.

This software must be used in the order indicated below:

- 1. Alternator configuration
- 2. Regulation mode:
 - Voltage regulation
 - Underspeed settings
 - Other types of regulation (PF, reactive power, manual) depending on the user's selections.
- 3. Faults and digital outputs
- 4. Monitors

Open «New configuration» from the menu bar, which takes you to the «Alternator Configuration» window. The parameters for this page are set in two parts: Alternator, Options.

The wiring scheme varies according to the characteristics specified by the user.





D510 C Automatic Voltage Regulators (AVRs)

Alternator

M EasyReg	In the dropdown lists or boxes, se
File Edit Parameters ?	1. The type of elternator
Generator setting Regulation mode Faults and digital output	1. The type of alternator
Generator	2. The length
Generator model:	3. The type of field excitation
Length:	4. The frequency
Field excitation system: 🗖 PMG 🗖 AREP 🗖 SHUNT 🔫	-3
Frequency nomination 50Hz 60Hz	5. The number of stator outputs
Number of stator outputs: 🔽 2 wires 🗖 6 wires	6. The stator connections
Stator connection diagram:	7. The voltage sensing
Voltage sensing: 🛛 🕅 Single phase 🗖 Three phases	(single or three-phase)

Note: The information relating to items 1, 2, 3 and 4 can be found on the nameplate.

[Expert mode]: the alternators list is more expanded. In this mode it is also possible to select the Service, the temperature rise class and the alternator power.

NB: FF and G electrical connections are dedicated to single phase application, no three-phase sensing is possible.

Stator connections: Click on the question mark to get help on the stator connections.

EasyReg 🖉 🖉
Fle Edit Parameters ?
enerator setting Regulation mode Faults and digital outputs Monitors
Generator Generator model LSA 44.2
Lengt: L12 Feld exclusion system: PMG ABEPF SHUIT
Freid exclusion system: PMCIPI AREP SHUNT Frequency nominat IP ISON: IF ISON: I
Stator outputs: Vites 6 vites
Stator connection diagram: CONNECTION: D 2
Volage sensing V Single Three phases of the sense of th
Coptions Findpointies serving Findpointies serving Covert Neurologies (C1) Covert Neurologies (C1) Covert Neurologies (C1) Strategies (C1) Covert Neurologies (C1)
Ratio
Generator voltage transformer (P.T.)
Pinay U (V): Secondary U (V): 1
Bus voltage transformer
Prinary U (V): Secondary U (V): 1
Step 1 Next >>>
D510C CONNECTED LSA 44.2 , L12, AREP, 50 Hz, 400 V Standard mode

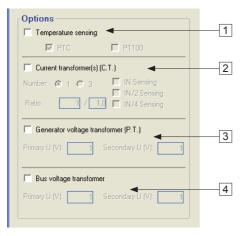
The alternator configuration is recalled at the screen left bottom



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D510 C Automatic Voltage Regulators (AVRs)

Options



To obtain the following options, tick the boxes:

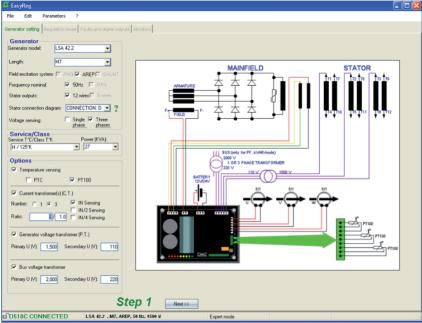
1. **Temperature sensors**, select either 1 PTC or 3 PT100s.

2. **Current transformers (CTs)**, select the number (1 or 3), the measurement (IN, IN/2 or IN/4) and the ratio. unless one CT is mandatory for parallel operation, PF or kVAR regulation, stator over current, unbalenced current.

3. Alternator voltage transformer, enter the voltage values at the primary and at the secondary if a transformer is connected..

4. **Bus voltage transformer**, enter the voltage values at the primary and at the secondary if a transformer is connected.

The electrical schematic below shows how the «wiring scheme» part changes according to the parameters selected.



After entering the data in this page, go to the second page by clicking «Next». In some cases, you will need to adjust the workscreen in order to access the «Next» button.



D510 C

Automatic Voltage Regulators (AVRs)

3.3.3.2 - Regulation mode

After entering the «Alternator Configuration» part settings, fill in the «Regulation Mode» part.



4 types of regulation are offered:

- Voltage
- Power factor (P.F.)
- Reactive power (kVAR)
- Manual (I exc)

Always setting begins with voltage regulation.

Caution, regulation of the reactive power PF and the quadrature droop can only be enabled if there is a CT on phase U and it has been selected.



A - Voltage regulation

This page consists of two parts :

- Voltage Regulation

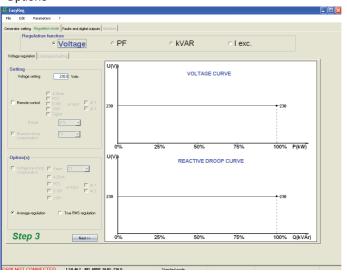
- Underspeed settings

Setting the parameters for this part starts with the «Voltage regulation» page and ends with the «Underspeed settings» page.

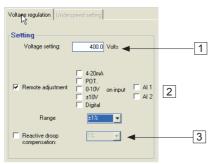
A1 - Voltage regulation

This page is split into two parts:

- Settings
- Options



A1.1 - Settings



1. The displayed value comes from Easyreg® database. It can be adjusted in the range \pm 10% maximum.

Expert Mode: The adjustment range can be extended to $\pm 30\%$



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D510 C Automatic Voltage Regulators (AVRs)

2. To set the voltage externally, tick the box, define by what means (POT, 0-10 V, etc) this setting will be made as well as the selected input (Al1 or Al2), then enter the desired setting range.

P Remote adjustment			+420 +400 +-380
Range	±5%	Nominal value adjustable at ±5% Precision adjustment can set the voltage	
Reactive droop compensation:	1%	setting from 380V to 420V	

3. If you wish to have voltage quadrature droop, tick the box and select the quadrature droop percentage.

This function is only available if a CT is used. It can be adjusted up to 10% maximum.

AT EasyReg				
File Edit Parameters ?		~		
Generator setting Regulation mode Faults and digital outputs	Monitors			
Voltage	° PF	⊂ kVAR	I exc.	
Voltage regulation Underspeed setting				
Setting Voltage setting: 400.0 Volta	U(V))	VOLTAGE	CURVE	
Image: Provide adjustment Image: Point on input Image: Point on input	404			
Range ±1% ▼ ▼ Reactive droop compensation: 3% ▼	Nominal value Precision adju setting from 3	adjustable at ±1% stment can set the voltage 95V to 404V 25% 50%	75%	100% P(kW)
Option(s)	U(V))	REACTIVE DE	ROOP CURVE	
Compensation:	404		Nominel value adjustable at ±1 Precision adjustment can set setting from 384V to 392V at 100% of GMAX.	% he votage
C 010/ C A12	400			
Average regulation C True RMS regulation				
Step 3	0%	25% 50%	75%	100% Q(kVÅr)
D510C CONNECTED LSA 43.2 , L65, PMG,	50 Hz, 400 V	Expert mode		



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A1.2 - Options

1. If you wish to have line drop compensation, tick the box and select the type of setting by a % value or an external setting. The standard setting is 3%.

	0	0		
EasyReg				
File Edit Parameters ?				
enerator setting Regulation mode Faults and digital outputs	Monitors			
Regulation function				
the second se	• PF	KVAR	 I exc. 	
Voltage	· FF	KVAR	Texc.	
Voltage regulation Underspeed setting				
1				
Setting				
Voltage setting: 400.0 Volts				
E 1 B 1				
- 4-20mA				
Remote adjustment 0-10V on input Al 1	U(V)			
E ±10V E Al 2		VOL TAG	ECURVE	
Bange ±1%				
Hange ±14 •				
F Reactive droop 3% +				
compensation:	404			
	400			408
Option(s)	396			1
	Nominal value	adjustable at ±1% stment can set the voltage 96V to 404V		
Voltage line droop Value: 3%	setting from 3	96Y to 404V		
□ 4-20mA				
F POT. on input	0%	25% 50%	75%	100% S(kVA)
C 0-10V C AI 2	070	2070 0070	1070	10070 O(KYA)
/ ±10√				
C Average regulation				
Step 3				

The function « Voltage line droop compensation » cannot be simultaneously activated with «reactive droop compensation».

EasyReg	
$\mathbf{ \odot}$	The LINE DR00P COMPENSATION cannot be activated when the REACTIVE DR00P COMPENSATION function is already activated. desactivate the REACTIVE DR00P COMPENSATION function to activate the LINE DR00P COMPENSATION
	OK

It is possible to impose the desired compensation by direct entry of the % value or make an external adjustment (10% max

- 2. Select which value regulation should apply to :
- mean value
- true rms value
- To go to the next step «Underspeed settings», click «Next».



Next >>



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D510 C Automatic Voltage Regulators (AVRs)

A2 - Underspeed settings

This page is split into three parts:

- Starting
- Underspeed
- Engine

A2.1 - Starting

Start 7	Factory setting: disabled
During 1,0 Second(s)	

To adjust Soft-start, check the box and select the duration between 0.1 s and 120 s (1 step = 0.1 s). Clicking on the question mark give help information on this function.

M EasyReg			- 🗆 🗙
File Edit Parameters ?			
Generator setting Regulation mode Faults and digital outputs Monitors Regulation function	Soft-start function: The soft-start function gradualy raise the votage during the engine starting independently of the frequency. This votage value is advassy similed by the UVE flow defined in setting. The adjustment is in seconds from 0.1s to 120.0s. Charge with soft-start at 30s Start	ା exc.	
Start (V,	con	UNDERSPEED CURVE	
Underspeed 200 Knee 48.0 Hz ? Stope 1.0 U/F			
Engine aid			
Upload settings to the controller card	10 20 J 20 40 50 24 48		<u>, izo f(Hz)</u> >
>500 NOT CONNECTED LSA 46.2 , M3, AREP, 50 Hz, 201	V Standard mode		



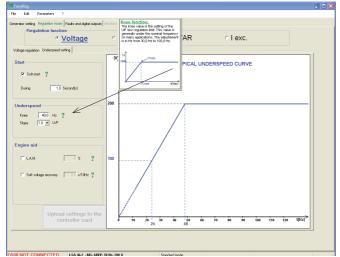
LEROY-SOMER	Installation and maintenance	4243 en - 2012.10 / e
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A2.2 - Underspeed

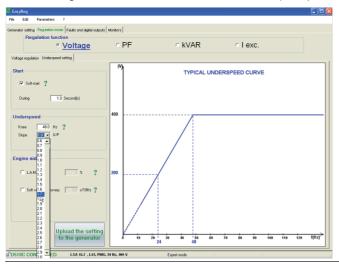


Factory setting: 48 Hz for 50 Hz 58 Hz for 60 Hz

1. Enter the knee-point value between 47.5 and 52.5 Hz (1 step = 0.1 Hz). An error message appears when the value displayed is outside the permitted range. The extended range is accessible in expert mode.



2. Enter the gradient value between 1.0 and 3.0 U/F (1 step = 0.1 U/F). Factory setting: 1/U/F.





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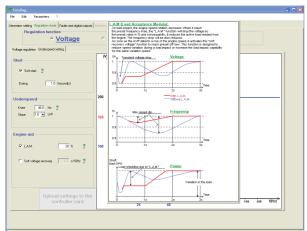
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A2.3 - Motor help

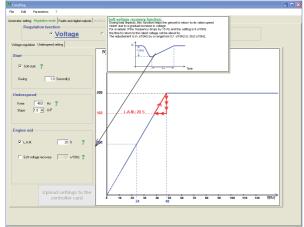


1. If the LAM function is required, tick the box and select its value between 0% and 30% (1 step = 1%).

Recommended setting: LAM 9% - U/F 1.7%



2. If you wish to have a gradual increase, tick the box and select the value between 0.1 s/10 Hz and 30.0 s/Hz (1 step = 0.1 s/10 Hz).



Save (see section 3, «Save» part).

Load the configuration in the regulator :

- By clicking on the button - Or by using the key F10
- Upload the setting to the generator
- Or PC→D500 in « Edition » menu

To configure another function, click the «Next» button and go to the corresponding page in this manual.



Next >>



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B - Regulation of the power factor

Caution: You can only enable selection of regulation by power factor PF or selection of regulation of the reactive power KVAR, and the quadrature droop, if there is a CT on phase U which has been enabled on the alternator configuration page.

This page is split into two parts:

- Digital inputs
- Settings

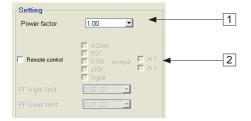
B1 - Digital inputs



Check the digital input on which the voltage match circuit has been placed in order to enable it. The second digital input is reserved for enabling power factor regulation mode.

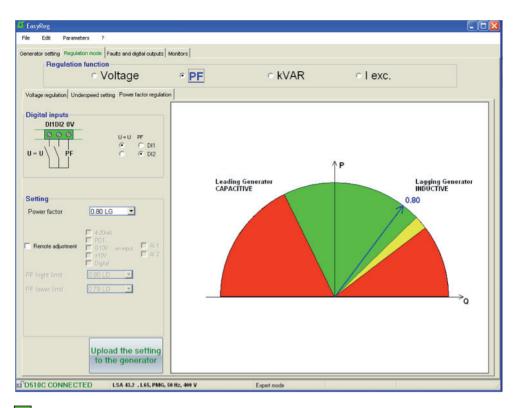
B2 - Settings

It is possible to set a fix value or use a remote adjustment in a predefined range.



1. Select the power factor value. The value depend on the alternator type.







Database Authorized area

Database not recommended area

Forbidden area

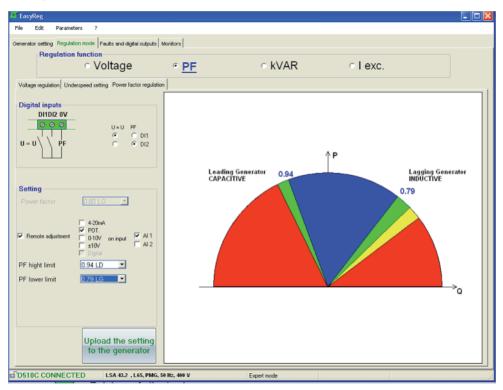
It is impossible to enter a reference value outside the limit values which are automatically set from the data on the alternator database.

Warning: When a value is outside the database recommended area, a message appears as indicated below.





2. To set the power factor externally, tick the box, select the source (POT, 0-10 V, etc) for this setting and also the input (Al1 or Al2). One of the inputs may be greyed-out if it is already being used by another function.



Remote adjustment operation area

Database Authorized area

Database not recommended area

Forbidden area

Save (see section 3, «Save» section). Load the settings into the AVR by clicking the following button :

Upload settings to the controller card



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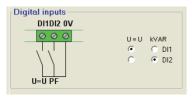
C - Regulation of the reactive power kVAR

Caution, regulation of the reactive power PF, and the quadrature droop can only be enabled if there is a CT on phase U and it has been configured.

This page is split into two parts:

- Digital inputs
- Settings

C1 - Digital inputs



Check the digital input on which the voltage match circuit has been placed in order to enable it. The second digital input is reserved for enabling reactive power regulation mode.

C2 - Settings

Settings	
KVAR 0.9	6 💽 OMAX
F Remote control	4-20mA F0T. 0-10V on input Al 1 d12 Digtal
	0 %
	I %.

1. Select the value of the reactive power according to the load. This value depends on the alternator type.



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Automatic Voltage Regulators (AVRs)			

It is possible to set a fix value or use a remote adjustment in a predefined range.

EasyReg				
File Edit Parameters ?				
Senerator setting Regulation mode Fauts and digital outputs N Regulation function	,	6		
 Voltage 	° PF	۴ <u>kVAR</u>	ା exc.	
Voltage regulation Underspeed setting kVAR regulation				1
U=U KVAR U=U LVAR U=U LVAR C DI1 U=U	L	eading Generator	↑ P	Lagging Generator
Setting KVAR 5% LG OMAX 422mA F0T. COTOV on input. COTOV on input. A11 A12 Remote adjustment Solution A12 Remote adjustment Solution A12 Remote adjustment Solution A12 Remote adjustment A12 Remote adjustment Solution A12 Remote adjustment A12 Remote adjustment Remote adjustment	ä	eading Generator APACITIVE		Lagging Generator INDUCTIVE
KVAR.lower limit 20% LG Upload the setting to the generator	100%		516	100 ³ Q
D510C CONNECTED LSA 43.2 , L65, PMG, 54	9 Hz, 400 V	Expert mode		
Database Authorized are	a	Database not reco	ommended area	Forbidden are

Warning: When a value is outside the database recommended area, a message appears as indicated below.

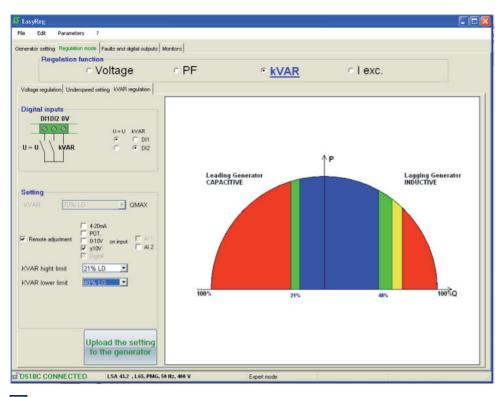




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2. To set the reactive power externally, tick the box, select the source (POT, 0-10 V, etc) for this setting and also the input (AI1 or AI2). One of the inputs may be greyed-out if it is already being used by another function.



Remote adjustment operation area

Database Authorized area

Database not recommended area



Save (see section 3, «Save» part).

Load the settings into the AVR by clicking the appropriate button.

Upload settings to the controller card



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D - Manual regulation: I exc

This page is split into three parts:

- PC (settings)
- External control
- Follower mode

The manual mode can be activated and adjusted either with the PC (via EasyReg software) or remotely. In that last case, a switch allowing the activation/ deactivation of the manual mode must be connected to one of the digital inputs and the excitation current setting is achieved by the remote analogue device through the Al1 or Al2.

D1 -	PC
------	----

	Setting		
PC	Enable manual mode	Manual ref	

Enter the desired excitation current value between 0.0 A and 10.0 A (1 step = 0.1 A). Manual mode is enabled by clicking the corresponding button.

D2 - External control

	External comand	↓ 420mÅ POT. 0.10V ↓ ±10V ↓ bigital	1
 External comand 	DI1DI2 OV		
	Manual Mode	Manual mode © DI1 © DI2	42

1. To set the excitation current externally, tick the box, select the source (POT, 0-10 V, etc) for this setting and also the input (Al1 or Al2). One of the inputs may be greyed-out if it is already being used by another function.

2. Check the digital input on which manual mode has been placed in order to activate it.



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D3 - Follower mode

If this function is enabled, it allows to switch in manual mode with initial setting value as a copy of the last excitation cirrent measurement before the switching.

Regulation function				
 Voltage 	° PF	kVAR	[◦] <u>I exc.</u>	
e regulation Underspeed setting Manual mode				
Anual mode ENABLE	700			1 1
Generator voltage I exc.	90%			
236.6 V 0.0 A	80%. 70%			
Setting	00 %			
Disable manual Manual ref	505			
mode	P 651			
	20%			
	10%			
Follower mode ? Upload the setti	ing			1 1
C Enable to the generate	or 10			1 1
External comand 4-20mA	003			
I Remote adjustment □ PDT. □ 10/ on inp	u [Al 1 76%			
10V	F AI 2			
E Digital	50%			
DI1DI2 OV	40%			
Mit Mit	anual mode 20%			

Save (see section 3, «Save» part).

Load the settings into the AVR by clicking the button :

Upload settings to the controller card



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D510 C Automatic Voltage Regulators (AVRs)

3.3.3 - Faults and digital outputs

This page is split into three parts in standard mode:

- Assignment of faults
- Assignment of digital outputs
- faults options

Faults affectation

The main faults can be supervised by assigning them to digital outputs.

Bit Parameters P Parameters	syReg					
Faults affectation AL1 AL2 D01 D02 Main fault C C C C C D01 D02 Loss of voltage sensing C C C C C C C C C D01 D02 Shot cicult fault C <thc< th=""> C <thc< th=""></thc<></thc<>	Edit Parameters	?				4
Ai 1 AL 2 D01 D02 Main fault C C C D01 D02 Loss of voltage sensing C C C Not used C C Shot circuit fault C C C C D1 D02 Not used C C Under excitation C	rator setting Regulation mod	e Faut	ts and c	ligital out	tputs M	onitors
Loss of voltage sensing C C C C Not used C C Shot cicuit fault C C C C C C C Under excitation C C C C C C C Over excitation on level C C C C C C C Over excitation on curve C C C C C C C Over temperature PTI001 C C C C Fault options Level PT1001 160 °C Over temperature PT1002 C C C Level PT1002 180 °C C Over temperature PT1003 C C C Level PT1003 180 °C C Unbalance stator current C C C Level PT1003 180 °C C Diver temperature PT1003 C C C Level PT1003 180 °C C Unbalance stator current C C C Level PT1003 180 °C C Diso in C C	Faults affectation	AL1	AL2	D01	D02	Information mode destination
Loss of voltage sensing C <td>Main fault</td> <td>0</td> <td>0</td> <td>0</td> <td>0</td> <td></td>	Main fault	0	0	0	0	
Shot circuit fualt C C C C C Under excitation C C C C C Over excitation on level C C C C Over excitation on level C C C C Over excitation on curve C C C C Over temperature PTC C C C C Over temperature PT1001 C C C C Over temperature PT1002 C C C Level PT1003 Over temperature PT1003 C C C Unbalance stator current C C C	Loss of voltage sensing	0	С	۲	0	Not used 🕫 C
Under excitation C C C C Manual mode Manual mode <t< td=""><td>Short circuit fault</td><td>С</td><td>С</td><td>o</td><td>0</td><td>u-u c c</td></t<>	Short circuit fault	С	С	o	0	u-u c c
Dver excitation on level C C C C Dver excitation on curve C C C C Dver votage C C C C Over temperature PT1001 C C C C Dver temperature PT1002 C C C Everl PT1001 Over temperature PT1002 C C C Dver temperature PT1003 C C Dver temperature PT1003 T Dver temperature PT1003 T Dver temperature PT1003 T	Under excitation	0	o	0	0	PF/ KVAR C @
Over voltage <	Over excitation on level	c	0	0	0	Manual mode C C
Over temperature PT1001 C C C Over temperature PT1001 C C C Over temperature PT1002 C C C Over temperature PT1003 C C C Unbalance stator current C C C Unbalance stator current C C C	Over excitation on curve	c	С	0	c	
Over temperature PT1001 O O Fault options Over temperature PT1002 O O Level PT1001 160 °C Over temperature PT1003 O O Level PT1002 161 °C Unbalance stator current O O Level PT1003 162 °C Unbalance stator current O O Detection from 102 °C In	Over voltage	۲	0	0	0	
Over temperature PT100-1 C C C Level PT100-1 160 °C Over temperature PT100-2 C C C Level PT100-2 160 °C Over temperature PT100-3 C C C Level PT100-3 160 °C Unbalance stator current C C C Unbalance threshold C 160 °C Unbalance stator current C C C C 20 °C IAVF3 everage	Over temperature PTC	c	c	0	0	
Over temperature PT100-3 C C Level PT100-3 161 Unbalance stator current C C Unbalance threshold 22 X1 AVR average Detection from S2 In	Over temperature PT100-1	c	۰	o	c	
Unbalance stator current C C C C Unbalance threshold 20 % I AVR average Detection from 50 % In	Over temperature PT100-2	c	C	0	c	Level P7100-2 160 °C
Unbelance stator current C C C C Detection from 53 % in	Over temperature PT100-3	0	c	0	0	Level P7100-3 160 °C
	Unbalance stator current	c	c	c	c	
	Stator overcurrent	c	c	0	c	

NOTA : The fault « Unbalance current » is only selectable if 3 CT are checked.

This page offers the possibility of assigning faults and operating modes to 4 outputs (AL1, AL2, D01 and D02).

Example of settings:

- Assignment of «Overvoltage» fault to AL1

- Assignment of «PT100-1 overtemperature» fault to AL2 with the maximum temperature set at 200°C

- Assignment of «Loss of voltage sensing» fault to DO1

- Assignment of «PF/kVAR» digital output to D02



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Faults options

It is possible to configure the thresholds for triggering certain faults:

- On temperature measurement (PT100)

- On stator current unbalance: it is possible to set the level for sensing and unbalancing level compare to the current mean value.

- On Stator Overcurrent: The current level above which the fault is activated can be set.

Information mode destination

The digital outputs DO1 and DO2 are assigned to « U = U », « PF / kVAR » and « manual mode » in priority.

The Expert mode offers other functions

T EasyReg									
File Edit Parameters	?								
Generator setting Regulation mo	de Faul	ts and d	ligital ou	tputs M	nitors				
Faults affectation					Information mode destination	Enable/disable of fa	ults		
Main fault		AL2					Enable	Disable	
mannauk		1	1		D01 D02	Loss of voltage sensing	•	0	
Loss of voltage sensing	C	C	C	0	Not used 🕫 🕫	I exc. protected	۲	C	
Short circuit fault	c	c	c	c	U=U C C	Over voltage protected	۲	c	
					PF/ kVAR C C	Grid Code Function	0	۲	?
Under excitation	0	0	0	R		Nominal field current		4.0	A
Over excitation on level	C	C	c	C	Manual mode C C	Logical Input/output			
					Start on Threshold ?		Enable	Disable	
Over excitation on curve	0	0	0	0	Enable	Inversion of DI1	0	۲	
Over voltage	0	C	c	C	% initial PwM 0.00	Inversion of D12	0	۲	
o ver vorage					Activation threshold [V] 0	Inversion of DO1	0	۲	2
Over temperature PTC	0	С	C	0		Inversion of DD2	0	۲	
	~	~	~	~	Fault options	Inversion of AL1	c		
Over temperature PT100-1	0	0	0	0	Level PT100-1 160 °C	Inversion of AL2	c		
Over temperature PT100-2	C	c	c	C	Level PT100-2 160 °C				
Over temperature PT100-3	0	c	c	0	Level PT100-3 160 rC	Digital external setting memorization	¢	¢	?
					Unbalance threshold 20 % LAVR average				
Unbalance stator current	C	C	C	0	Detection from 50 % in			DS	10C
Stator overcurrent	c	c	¢	e	AVR Overcurrent Threshold 100 % In			OPT	TIONS
D510C CONNECTED	L	SA 43.2	, L65,	PMG, 50	Hz, 400 V Expert mode		_	_	_



• [Expert mode] Start on Threshold

Activate and set this function.

• [Expert mode] Enable/disable of Faults

Allows to activate/deactivate the regulator protections (overvoltage, over-excitation,..).

• [Expert mode] Grid Code Function

Allows to activate/deactivate this function.

• [Expert mode] Nominal excitation current

This value comes from the database but can be changed by the user

[Expert mode] digital input/ outputs

It is possible to reverse these digital IOs.

• [Expert mode] Digital external setting memorization

This function is use in « +/-» mode; it allows to keep the regulation mode adjustment when passing from one mode to another regulation mode.

3.3.4 - [Expert mode] D510C Options

The regulator D510C offers several functions accessible by clicking on the button



• [Expert mode] rotating diode bridge fault

Activate/deactivate the rotating diodes state supervision of exciter In case of the supervision of activation of this feature, the « shutdown lexc » function must be also enabled.

• [Expert mode] Generator current limitation

Set this function

• [Expert mode] CAN network configuration

Enable CAN Set the data transfer rate Choose the regulator identifier Select the broadcast protocol (J1939 and/or Owner CAN) In the case of Owner CAN, choose the parameters to broadcast.



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otating diod	e bridge fault		Generator current limitation
ODE Fault autdown lexo	Enabled (C C C C	Current limitation Current limitation Current limitation value (%In) 110 Regulation gain 5
N Network	configuration		
abled Disabled C Data transfert R Broadcast p	arameters	n) 💌	CAN activation delay (s) 0.0 D510 ID 144 0x90 2 ? I Broadcast J1939 ?
	ent parameters	- ?	Sending period (ms) 50
Parameter 2 les			
Parameter 3 Gr	enerator voltage one phas	e	
Parameter 4	ed state		

Click on OK to validate the configuration Click on OK and Upload

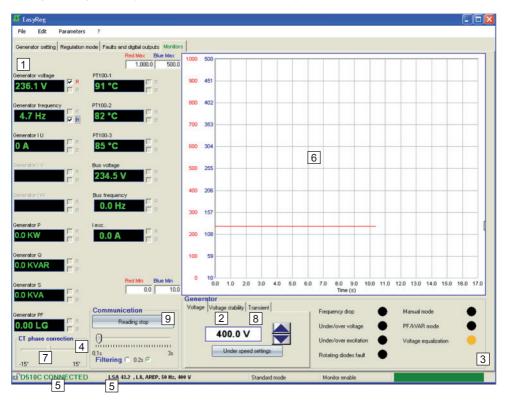
Nota: the key F10 doesn't allow to transfer the CAN parameters. **Nota**: The selection « Broadcast J1939 » locks the transfer rate at 250Kb/s



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3.3.5 - Monitors

This page is only displayed when the AVR is connected to the computer. It consists of 15 digital control screens (voltage, frequency, current, etc), an analogue screen, 3 adjustment tabs (voltage, voltage stability and transient test) and displays the LED states.



1. The 15 windows display the alternator values compared to the enabled options.

By selecting 1 CT you can display: Alternator I U, Alternator P, Alternator Q, Alternator S, Alternator PF.

By selecting 3 CTs you can also display: Alternator I V, Alternator I W.

By selecting PT100 temperature sensors you can display: PT100-1, PT100-2, PT100-3.

2. Click this button to adjust the stability.

3. This part displays the LED status.

4. Click on the button «start reading» to display the values. The filtring parameters can also be set.



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5. These 2 indications show that the AVR is connected and its characteristics have been selected.

6. 2-signal display screen. Simply tick in one of the boxes (R or B) and set the scale (Max-Min).

7. The CT phase angle should be compensated to improve the accuracy of the display by moving the «CT phase angle correction» slider.

8. Transient test: **Do not start this test if in load operation.**

- Click on «Transient test»,
- The test voltage level setting window appears,
- Enter the values, confirm, wait for the process to end.

Note: Set the minimum and maximum values within the range permitted by the generator voltage sensing device.

9. To start reading, click «Start reading». The filter value can be adjusted by 0.1 s to 3 s.

10. The voltage to track is displayed and can be adjusted thanks to the buttons The setting of Underspeed is also directly accessible.



The approach is the same for the other regulation modes (PF, kVAR et lexc)



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Transient test

It is possible to configure a transient test in order to evaluate the regulation performances.

EasyReg File Parameters Edit Generator setting Regulation mode Faults and digital outputs Elue Max 500 1000 1,000.0 500.0 PT100-451 900 230.1 V 74 °C 800 402 PT100-2 4.7 Hz 67 °C 700 353 PT100.3 0 A 69 °C 600 304 enerator I V Bus voltage 500 255 0 A 228.0 V 400 206 erator I W 0 A 0.0 Hz 300 157 0.0 KW 200 108 0.0 A 100 59 0.0 KVAR 0 10 Elue Min 1.0 2.0 3.0 4.0 5.0 6.0 7.0 8.0 9.0 10.0 11.0 12.0 13.0 14.0 15.0 16.0 17.0 0.0 Time (s) 0.0 KVA Generator Voltage Voltage stability Transient Communication Frequency drop Manual mode Start reading 0.00 LG PF/kVAB mode Under/over voltage **CT** phase correction 0 Under/over excitation Voltage equalizat Rotating diodes fault Fault Filtering C 0.2s @ -15 15' LSA 43.2 , L65, PMG, 50 Hz, 400 V Expert mode

[Expert mode] monitors

The graph is memorized using up to 150 000 sliding points.

It is possible to move the curve by clicking on the button

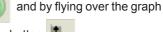
[Expert mode] An auto-scale can be obtained by clicking on the button

[Expert mode] Fault reset

It is possible to clear fault display by clicking on the button

[Expert mode] PID

The digital potentiometer is replaced by the PID numerical values in READ/WRITE mode.







Fault

reset



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Voltage	Voltage stability Tr	ansient
	Proportional:	54
	Intégrate:	3
	Derivate:	300
	Gain:	100
	Scale:	0

Narning: A wrong setting c	of the PID can c	lamage the alternator
	Narning: A wrong setting o	Narning: A wrong setting of the PID can o

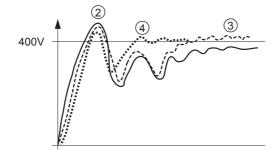
PID setting methodology:

Please use Transient Test:

- 1 Initial conditions:
 - Proportionnal = 10
 - Integral = 1
 - Derivative = 1
 - Gain = 10
 - Scale = 1

2 Adjust the proportional part to obtain a response as given in the figure below.

- ③ Adjust the integral part to have the output voltage in steady states equal to desired voltage (reference voltage).
- (4) Adjust the derivative part to obtain response without oscillations.
- 5 Adjust the gain if necessary.
- 6 Change the scale value if the setting is unsuccessful and go back to step 2.





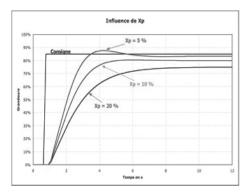
PID controller

The PID controller is an important system for the AVR. It is used to adjust the static gain with the proportional part, stability with the derivative action and speed thanks to the integral action.

- Proportional action

This action affects the speed.

The smaller the proportional band, the lower the static error and the shorter the response time.



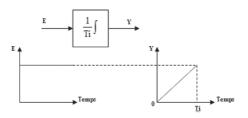
If Xp (proportional band) is small, there may be an overrun but if Xp is too large, the static error is greater.

- Integral action

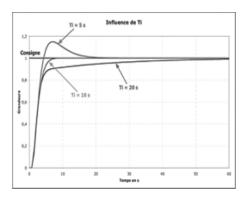
This action changes over time and is used to reduce the static error.

It is filled in by the «Integral in relation to the time» mathematical operator.

In an AVR, the integral action is defined using one of two parameters: Ti integral time or Ki integral gain.



The smaller Ti is, the more quickly the value of output Y increases. The time Ti is the time it takes command Y to increase with the value of input E.

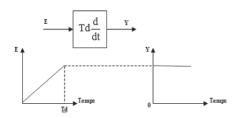


If Ti is too short, there is a strong possibility that the reference will be exceeded but if Ti is too long, the measurement takes longer to reach the reference.

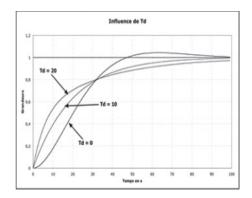


- Derivative action

This action amplifies abrupt variations in the reference. It has the opposite action to the integral action. This function is filled in by the «Derivative in relation to the time» mathematical operator. In an AVR, the derivative action is defined using the derivative time Td.



The larger Ti is, the greater the value of the Y output. The time Td is the time it takes input E to increase by the value of output Y.



Si Td est trop long, une erreur statique apparaît mais si Td est très court, la réponse est plus longue et un dépassement de la consigne se forme.

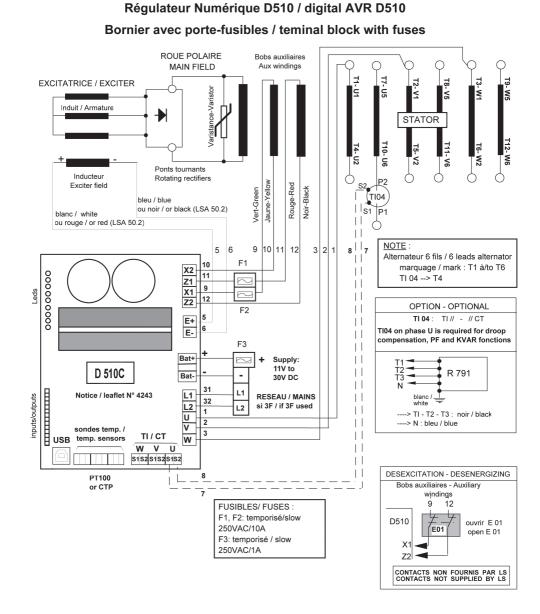
The table below summarises the effects which may be influenced by the PID actions.

PID controller	Effect
Proportional action	Speed
Integral action	Accuracy
Derivative action	Stability



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	inotaliation and maintenance	

4 - CONNECTION DIAGRAMS

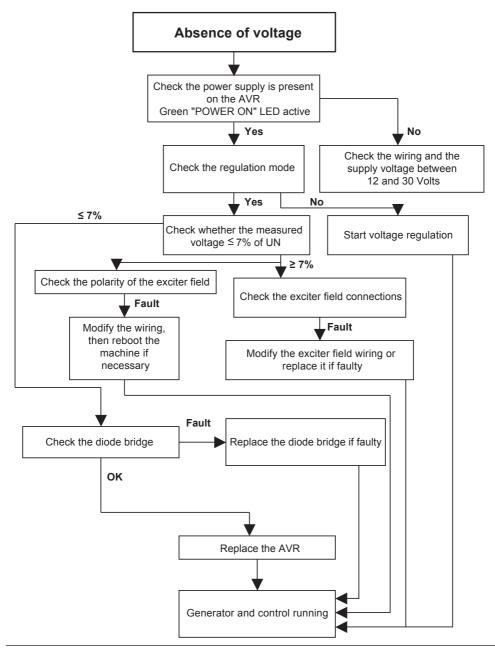




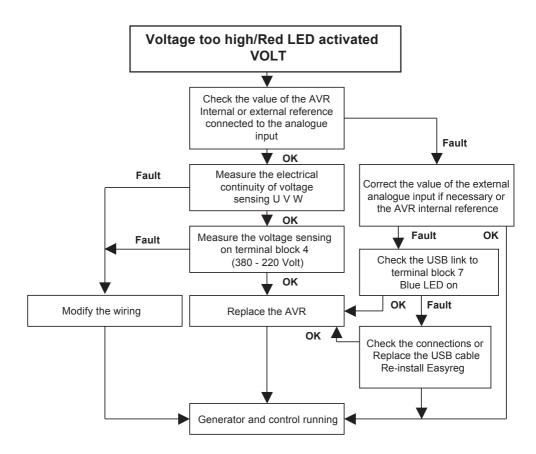
Installation and maintenance

D510 C Automatic Voltage Regulators (AVRs)

5 - FAULT FLOW CHARTS

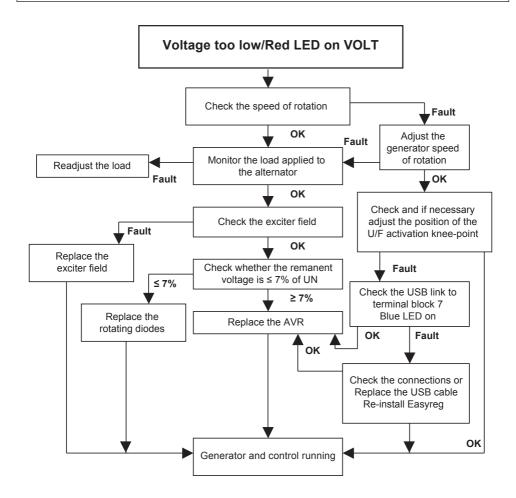




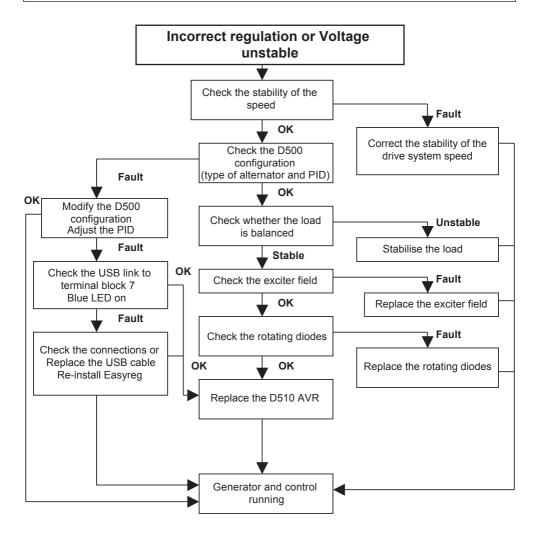




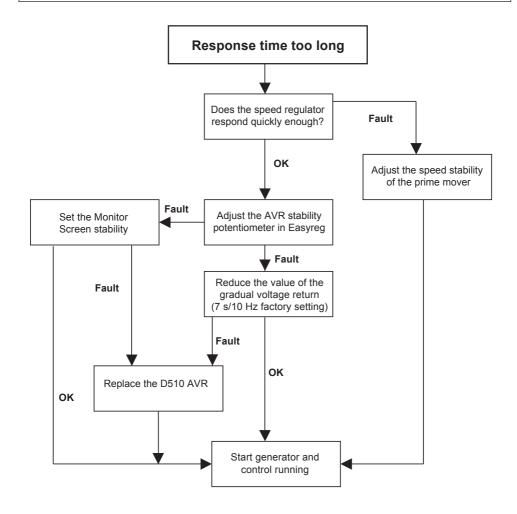
D510 C



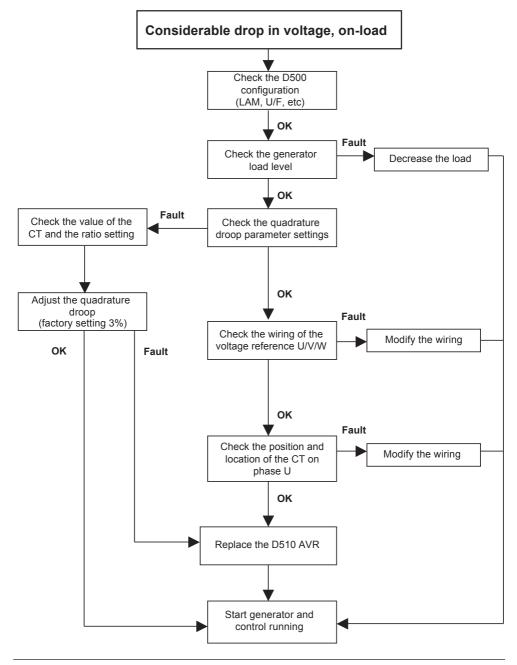








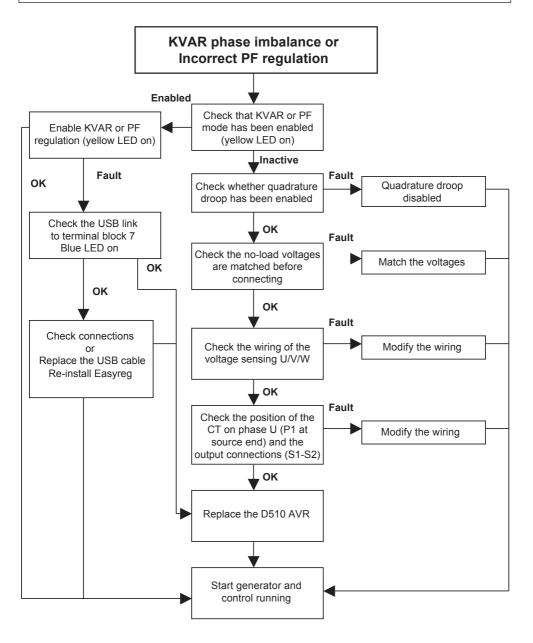






Installation and maintenance

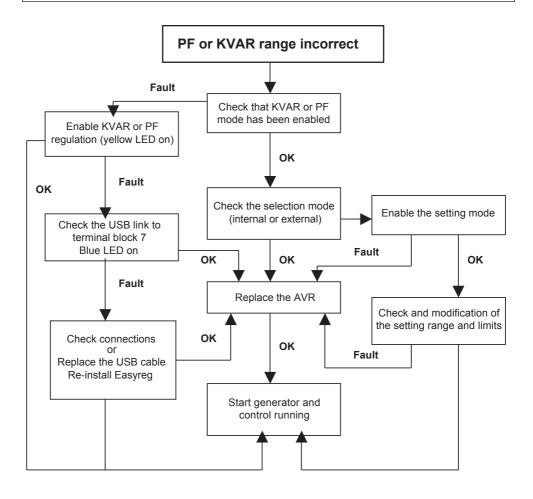
D510 C





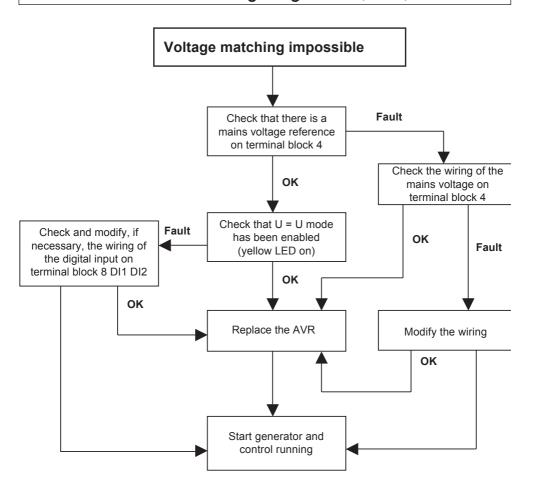
LEROY-SOMER	Ins

Installation and maintenance

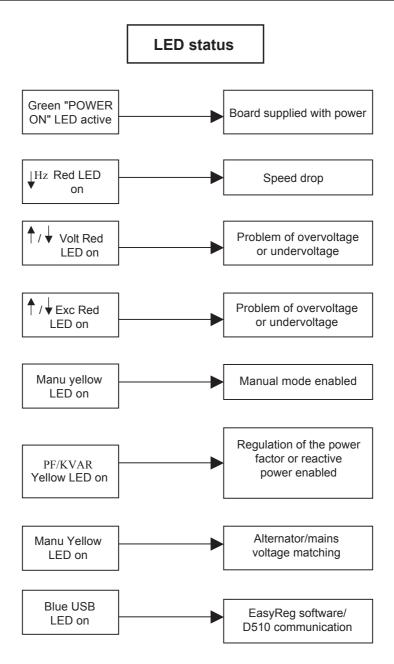
















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